

Quaternion Space-time (Part 2):

Pauli Matrices and Dirac Matrices

The Pauli matrices are defined as follows:

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Their multiplication table is:

$\times$	I	σ_1	σ_2	σ_3
I	I	σ_1	σ_2	σ_3
σ_1	σ_1	I	$i\sigma_3$	$-i\sigma_2$
σ_2	σ_2	$-i\sigma_3$	I	$i\sigma_1$
σ_3	σ_3	$i\sigma_2$	$-i\sigma_1$	I

There is an isomorphism from the span of the quaternions $\{\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}\}$ to the span of $\{I, i\sigma_1, i\sigma_2, i\sigma_3\}$ given by $(\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}) \leftrightarrow (I, -i\sigma_1, -i\sigma_2, -i\sigma_3)$ or by $(\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}) \leftrightarrow (I, i\sigma_3, i\sigma_2, i\sigma_1)$.

The Lie group $SU(2)$ given by $\{a\mathbf{1} + b\mathbf{i} - c\mathbf{j} + d\mathbf{k} : a^2 + b^2 + c^2 + d^2 = 1\}$ is diffeomorphic to $S^3 = \{a\mathbf{1} + b\mathbf{i} + c\mathbf{j} + d\mathbf{k} : a^2 + b^2 + c^2 + d^2 = 1\}$ and has as generators the set $\{\mathbf{i}, -\mathbf{j}, \mathbf{k}\} \simeq \{-i\sigma_1, i\sigma_2, -i\sigma_3\}$. $SU(2)$ is used in the description of electroweak interactions and beta decay.

The Dirac matrices (in contravariant form) are:

$$\gamma^0 = \begin{pmatrix} I_2 & 0 \\ 0 & -I_2 \end{pmatrix} \quad \gamma^1 = \begin{pmatrix} 0 & \sigma_1 \\ -\sigma_1 & 0 \end{pmatrix}$$

$$\gamma^2 = \begin{pmatrix} 0 & \sigma_2 \\ -\sigma_2 & 0 \end{pmatrix} \quad \gamma^3 = \begin{pmatrix} 0 & \sigma_3 \\ -\sigma_3 & 0 \end{pmatrix}$$

Their multiplication table is:

$\times$	γ^0	γ^1	γ^2	γ^3
γ^0	I	$\gamma^0\gamma^1$	$\gamma^0\gamma^2$	$\gamma^0\gamma^3$
γ^1	$-\gamma^0\gamma^1$	$-I$	$-i\sigma_3I$	$i\sigma_2I$
γ^2	$-\gamma^0\gamma^2$	$i\sigma_3I$	$-I$	$-i\sigma_1I$
γ^3	$-\gamma^0\gamma^3$	$-i\sigma_2I$	$i\sigma_1I$	$-I$

and in terms of quaternions

$\times$	γ^0	γ^1	γ^2	γ^3
γ^0	I	$\gamma^0\gamma^1$	$\gamma^0\gamma^2$	$\gamma^0\gamma^3$
γ^1	$-\gamma^0\gamma^1$	$-I$	$\mathbf{k}I$	$-\mathbf{j}I$
γ^2	$-\gamma^0\gamma^2$	$-\mathbf{k}I$	$-I$	$\mathbf{i}I$
γ^3	$-\gamma^0\gamma^3$	$\mathbf{j}I$	$-\mathbf{i}I$	$-I$

The D'Alembert operator $\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2$ in the relativistic wave equation

$$(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2)\psi = 0$$

can be expressed as $\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 = (\frac{1}{c} \gamma^0 \frac{\partial}{\partial t} + \gamma^1 \frac{\partial}{\partial x} + \gamma^2 \frac{\partial}{\partial y} + \gamma^3 \frac{\partial}{\partial z})^2$.

We can construct a representation of the quaternions in $M_{4 \times 4}(\mathbf{C})$:

$$(\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}) = (I, \gamma^2\gamma^3, \gamma^3\gamma^1, \gamma^1\gamma^2)$$

It is not difficult to check that this construction produces the required properties of quaternions.

Consider the following matrices in $M_{4 \times 4}\{0, \pm 1\}^*$:

$$\begin{aligned}
E_0 &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \\
E_1 &= \begin{pmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \\
E_2 &= \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix} \\
E_3 &= \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}
\end{aligned}$$

$$\begin{aligned}
E_4 &= \begin{pmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \\
E_5 &= \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \\
E_6 &= \begin{pmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \\
E_7 &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}
\end{aligned}$$

Their multiplication table is

$\times$	E_0	E_1	E_2	E_3	E_4	E_5	E_6	E_7
E_0	E_0	E_1	E_2	E_3	E_4	E_5	E_6	E_7
E_1	E_1	$-E_0$	E_3	$-E_2$	E_5	$-E_4$	E_7	$-E_6$
E_2	E_2	E_3	$-E_0$	$-E_1$	E_6	E_7	$-E_4$	$-E_5$
E_3	E_3	$-E_2$	$-E_1$	E_0	E_7	$-E_6$	$-E_5$	E_4
E_4	E_4	E_5	$-E_6$	$-E_7$	$-E_0$	$-E_1$	E_2	E_3
E_5	E_5	$-E_4$	$-E_7$	E_6	$-E_1$	E_0	E_3	$-E_2$
E_6	E_6	E_7	E_4	E_5	$-E_2$	$-E_3$	$-E_0$	$-E_1$
E_7	E_7	$-E_6$	E_5	$-E_4$	$-E_3$	E_2	$-E_1$	E_0

We observe that

$\times$	E_0	E_2	E_4	E_6
E_0	E_0	E_2	E_4	E_6
E_2	E_2	$-E_0$	E_6	$-E_4$
E_4	E_4	$-E_6$	$-E_0$	E_2
E_6	E_6	E_4	$-E_2$	$-E_0$

has the same multiplicative structure as the quaternions:

$\times$	1	i	j	k
1	1	i	j	k
i	i	-1	k	-j
j	j	-k	-1	i
k	k	j	-i	-1

giving the isomorphism $(\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}) \leftrightarrow (E_0, E_2, E_4, E_6)$.

Using the correspondence $(\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}) \leftrightarrow (I, -i\sigma_1, -i\sigma_2, -i\sigma_3)$,

$\times$	E_0	E_3	E_5	E_7
E_0	E_0	E_3	E_5	E_7
E_3	E_3	E_0	$-E_6$	E_4
E_5	E_5	E_6	E_0	$-E_2$
E_7	E_7	$-E_4$	E_2	E_0

has the same multiplicative structure as the Pauli matrices:

$\times$	I	σ_1	σ_2	σ_3
I	I	σ_1	σ_2	σ_3
σ_1	σ_1	I	$i\sigma_3$	$-i\sigma_2$
σ_2	σ_2	$-i\sigma_3$	I	$i\sigma_1$
σ_3	σ_3	$i\sigma_2$	$-i\sigma_1$	I

giving the isomorphism $(I, \sigma_1, \sigma_2, \sigma_3) \leftrightarrow (E_0, E_3, E_5, E_7)$.

The group $\mathbf{E} = \{\pm E_0, \pm E_1, \pm E_2, \pm E_3, \pm E_4, \pm E_5, \pm E_6, \pm E_7\}$ contains the Pauli matrices $\{E_3, E_5, E_7\}$ as a subset and the quaternion group $\{\pm E_0, \pm E_2, \pm E_4, \pm E_6\}$ as a subgroup. Any group containing the Pauli matrices must also contain the quaternion group as a subgroup. E is the smallest such group with that property.

Since E_1 commutes with the other E 's we can write

$\times$	$E_1 E_3$	$E_1 E_5$	$E_1 E_7$
$E_1 E_3$	$-E_0$	E_6	$-E_4$
$E_1 E_5$	$-E_6$	$-E_0$	E_2
$E_1 E_7$	E_4	$-E_2$	$-E_0$

Then using the following table:

$\times$	γ^0	γ^1	γ^2	γ^3
γ^0	I	$\gamma^0\gamma^1$	$\gamma^0\gamma^2$	$\gamma^0\gamma^3$
γ^1	$-\gamma^0\gamma^1$	$-I$	$\mathbf{k}I$	$-\mathbf{j}I$
γ^2	$-\gamma^0\gamma^2$	$-\mathbf{k}I$	$-I$	$\mathbf{i}I$
γ^3	$-\gamma^0\gamma^3$	$\mathbf{j}I$	$-\mathbf{i}I$	$-I$

we observe there is an isomorphism $(E_0, E_1E_3, E_1E_5, E_1E_7) \leftrightarrow (I, \gamma^1, \gamma^2, \gamma^3)$.

The group $\mathbf{F} = \{\pm\gamma^0, \pm\gamma^1, \pm\gamma^2, \pm\gamma^3, \pm\gamma^0\gamma^1, \pm\gamma^0\gamma^2, \pm\gamma^0\gamma^3, \pm\mathbf{1}, \pm\mathbf{i}, \pm\mathbf{j}, \pm\mathbf{k}\}$ contains the Dirac matrices $\{\gamma^0, \gamma^1, \gamma^2, \gamma^3\}$ as a subset and the quaternion group $\{\pm\mathbf{1}, \pm\mathbf{i}, \pm\mathbf{j}, \pm\mathbf{k}\}$ as a subgroup. Any group containing the Dirac matrices must also contain the quaternion group as a subgroup. F is the smallest such group with that property.

Note that $\mathbf{E}$ can be written as $\mathbf{E} = \{\pm E_0, \pm E_1, \pm E_2, \pm E_3, \pm E_4, \pm E_5, \pm E_6, \pm E_7\} = \{\pm\mathbf{1}, \pm i\mathbf{1}, \pm\mathbf{i}, \pm i\mathbf{i}, \pm\mathbf{j}, \pm i\mathbf{j}, \pm\mathbf{k}, \pm i\mathbf{k}\}$.

We can find the solutions of the Dirac equation in terms of the E s defined above.

Since $E_1^2 = -E_0$, $\hat{E} = E_1\partial_0$ is the energy operator and $\hat{p}_i = -E_1\partial_i$ is the i -th momentum operator, the Dirac Hamiltonian can be written as

$$H = -\Sigma_{n=3,5,7} \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix} \begin{pmatrix} \hat{p}_{(n-1)/2} \\ \hat{p}_{(n-1)/2} \end{pmatrix} + m \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix}$$

Recall that $-E_3E_1 = E_2$, $-E_5E_1 = E_4$, and $-E_7E_1 = E_6$. Assume $H\psi_L = \hat{E}\psi_L$ and $H\psi_R = -\hat{E}\psi_R$. Then setting $H \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix} \begin{pmatrix} \partial_0\psi_L \\ \partial_0\psi_R \end{pmatrix}$, we can write the Dirac equation as

$$\begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix} \begin{pmatrix} \partial_0\psi_L \\ \partial_0\psi_R \end{pmatrix} + \Sigma_{n=2,4,6} \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix} \begin{pmatrix} \partial_{n/2}\psi_L \\ \partial_{n/2}\psi_R \end{pmatrix} - m \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \mathbf{0}$$

which gives us the two equations:

$$\begin{aligned} E_1\partial_0\psi_L - (\Sigma_{n=2,4,6}E_n\partial_{n/2})\psi_R &= mE_0\psi_L \\ E_1\partial_0\psi_R - (\Sigma_{n=2,4,6}E_n\partial_{n/2})\psi_L &= -mE_0\psi_R \end{aligned}$$

Since $E_1\partial_0$ is the energy operator the above equations are equivalent to

$$E\psi_L - (\Sigma_{n=2,4,6}E_n\partial_{n/2})\psi_R = m\psi_L \quad (1)$$

$$E\psi_R - (\Sigma_{n=2,4,6}E_n\partial_{n/2})\psi_L = -m\psi_R \quad (2)$$

Then

$$\psi_L = \frac{\Sigma_{n=2,4,6}E_n\partial_{n/2}}{E-m}\psi_R \quad (3)$$

$$\psi_R = \frac{\Sigma_{n=2,4,6}E_n\partial_{n/2}}{E+m}\psi_L \quad (4)$$

Writing $\eta = \Sigma_{n=2,4,6}E_n\partial_{n/2}$ and substituting (4) into (1):

$$(E-m)\psi_L - \eta\frac{\eta}{E+m}\psi_L = 0$$

$$\eta^2 = (E_2\partial_x + E_4\partial_y + E_6\partial_z)^2 = -\partial_x^2 - \partial_y^2 - \partial_z^2$$

and since $-E_1\partial_i = \hat{p}_i$ and $E_1^2 = -E_0$ we have $\eta^2 = \hat{p}^2$

$$(E-m)\psi_L - \eta\frac{\eta}{E+m}\psi_L = 0 \text{ implies}$$

$$(E-m)\psi_L - \frac{\hat{p}^2}{E+m}\psi_L = 0.$$

$$\text{Then } [(E+m)(E-m) - p^2]\psi_L = 0.$$

So, $(E^2 - p^2 - m^2)\psi_L = 0$ and similarly $(E^2 - p^2 - m^2)\psi_R = 0$. Since the wave functions are assumed to be non-zero, $E^2 - p^2 = m^2$, which is consistent with the 4-vector magnitude-squared.

Recall that $-E_3E_1 = E_2$, $-E_5E_1 = E_4$, and $-E_7E_1 = E_6$ so we can re-write equations (3) and (4) as:

$$\psi_L = \frac{-\Sigma_{n=3,5,7}E_nE_1\partial_{(n-1)/2}}{E-m}\psi_R \quad (5)$$

$$\psi_R = \frac{-\Sigma_{n=3,5,7}E_nE_1\partial_{(n-1)/2}}{E+m}\psi_L \quad (6)$$

Recall that $-E_1\partial_i = \hat{p}_i$ so we can re-write equations (5) and (6) as:

$$\psi_L = \frac{\Sigma_{n=3,5,7}E_n\hat{p}_{(n-1)/2}}{E-m}\psi_R \quad (7)$$

$$\psi_R = \frac{\Sigma_{n=3,5,7}E_n\hat{p}_{(n-1)/2}}{E+m}\psi_L \quad (8)$$

We can write $\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}$ as:

$$\Pi = \begin{pmatrix} \hat{p}_z & 0 & \hat{p}_x & \hat{p}_y \\ 0 & \hat{p}_z & -\hat{p}_y & \hat{p}_x \\ \hat{p}_x & -\hat{p}_y & -\hat{p}_z & 0 \\ \hat{p}_y & \hat{p}_x & 0 & -\hat{p}_z \end{pmatrix}$$

Then we have the following products:

$$\Pi \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} \hat{p}_z & 0 \\ 0 & \hat{p}_z \\ \hat{p}_x & -\hat{p}_y \\ \hat{p}_y & \hat{p}_x \end{pmatrix} \text{ and } \Pi \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} \hat{p}_x & \hat{p}_y \\ -\hat{p}_y & \hat{p}_x \\ -\hat{p}_z & 0 \\ 0 & -\hat{p}_z \end{pmatrix}$$

For $E \geq m$ two linearly independent solutions are

$$\phi = \left[\frac{1}{E+m} \begin{pmatrix} p_z & 0 \\ 0 & p_z \\ p_x & -p_y \\ p_y & p_x \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \right] e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

and

$$\phi = \left[\frac{1}{E+m} \begin{pmatrix} p_x & p_y \\ -p_y & p_x \\ -p_z & 0 \\ 0 & -p_z \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} \right] e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

For $E \leq -m$ two linearly independent solutions are

$$\phi = \left[\frac{1}{E-m} \begin{pmatrix} p_z & 0 \\ 0 & p_z \\ p_x & -p_y \\ p_y & p_x \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \right] e^{E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

and

$$\phi = \left[\frac{1}{E-m} \begin{pmatrix} p_x & p_y \\ -p_y & p_x \\ -p_z & 0 \\ 0 & -p_z \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} \right] e^{E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

The matrices $\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$ and $\begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix}$ correspond to the two spin states

of a particle.

Verification of solutions:

Case $E \geq m$ with spin '+':

$$\begin{aligned}
\phi &= \left[\frac{1}{E+m} \begin{pmatrix} p_z & 0 \\ 0 & p_z \\ p_x & -p_y \\ p_y & p_x \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \right] e^{-E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& [E_1\partial_t - (\Sigma_{n=2,4,6}E_n\partial_{n/2})]\phi \\
&= E_1\partial_t \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{-E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& - (\Sigma_{n=2,4,6}E_n\partial_{n/2}) \frac{1}{E+m} \begin{pmatrix} \hat{p}_z & 0 \\ 0 & \hat{p}_z \\ \hat{p}_x & -\hat{p}_y \\ \hat{p}_y & \hat{p}_x \end{pmatrix} e^{-E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
&= E_1\partial_t \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{-E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& - (\Sigma_{n=2,4,6}E_n\partial_{n/2}) \frac{\Sigma_{n=3,5,7}E_n\hat{p}_{(n-1)/2}}{E+m} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{-E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
&= \begin{pmatrix} E & 0 \\ 0 & E \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{-E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& - (\Sigma_{n=2,4,6}E_n\partial_{n/2}) \frac{\Sigma_{n=3,5,7}E_n\hat{p}_{(n-1)/2}}{E+m} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{-E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
&= E\psi_L - (\Sigma_{n=2,4,6}E_n\partial_{n/2})\psi_R.
\end{aligned}$$

Furthermore, $E\psi_L - (\Sigma_{n=2,4,6}E_n\partial_{n/2})\psi_R = m\psi_L$

because $(\Sigma_{n=2,4,6} E_n \partial_{n/2})(\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}) = (\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2})^2$

$$= \hat{p}_x^2 + \hat{p}_y^2 + \hat{p}_z^2$$

and $E - \frac{p_x^2 + p_y^2 + p_z^2}{E+m} = m$ since $(E-m)(E+m) - (p_x^2 + p_y^2 + p_z^2) = 0$.

Case $E \geq m$ with spin '-':

$$\begin{aligned} \phi &= \left[\frac{1}{E+m} \begin{pmatrix} p_x & p_y \\ -p_y & p_x \\ -p_z & 0 \\ 0 & -p_z \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} \right] e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})} \\ &= [E_1 \partial_t - (\Sigma_{n=2,4,6} E_n \partial_{n/2})] \phi \\ &= E_1 \partial_t \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})} \\ &\quad - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{1}{E+m} \begin{pmatrix} \hat{p}_x & \hat{p}_y \\ -\hat{p}_y & \hat{p}_x \\ -\hat{p}_z & 0 \\ 0 & -\hat{p}_z \end{pmatrix} e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})} \\ &= E_1 \partial_t \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})} \\ &\quad - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}}{E+m} \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})} \\ &= \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ E & 0 \\ 0 & E \end{pmatrix} e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})} \\ &\quad - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}}{E+m} \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})} \end{aligned}$$

$$= E\psi_L - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \psi_R.$$

$$\text{Furthermore, } E\psi_L - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \psi_R = m\psi_L$$

$$\text{because } (\Sigma_{n=2,4,6} E_n \partial_{n/2}) (\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}) = (\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2})^2$$

$$= \hat{p}_x^2 + \hat{p}_y^2 + \hat{p}_z^2$$

$$\text{and } E - \frac{p_x^2 + p_y^2 + p_z^2}{E+m} = m \text{ since } (E-m)(E+m) - (p_x^2 + p_y^2 + p_z^2) = 0.$$

Case $E \leq -m$ with spin '+':

$$\begin{aligned} \phi &= [\frac{1}{E-m} \begin{pmatrix} p_z & 0 \\ 0 & p_z \\ p_x & -p_y \\ p_y & p_x \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}] e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\ & [E_1 \partial_t - (\Sigma_{n=2,4,6} E_n \partial_{n/2})] \phi \\ &= -E_1 \partial_t \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\ & - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{1}{E-m} \begin{pmatrix} \hat{p}_z & 0 \\ 0 & \hat{p}_z \\ \hat{p}_x & -\hat{p}_y \\ \hat{p}_y & \hat{p}_x \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\ &= -E_1 \partial_t \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\ & - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}}{E-m} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\ &= \begin{pmatrix} E & 0 \\ 0 & E \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \end{aligned}$$

$$\begin{aligned}
& -(\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}}{E-m} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& = E\psi_R - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \psi_L.
\end{aligned}$$

$$\text{Furthermore, } E\psi_R - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \psi_L = -m\psi_R$$

$$\text{because } (\Sigma_{n=2,4,6} E_n \partial_{n/2})(\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}) = (\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2})^2$$

$$= \hat{p}_x^2 + \hat{p}_y^2 + \hat{p}_z^2$$

$$\text{and } E - \frac{p_x^2 + p_y^2 + p_z^2}{E-m} = -m \text{ since } (E+m)(E-m) - (p_x^2 + p_y^2 + p_z^2) = 0.$$

Case $E \leq -m$ with spin '-':

$$\begin{aligned}
\phi & = [\frac{1}{E-m} \begin{pmatrix} p_x & p_y \\ -p_y & p_x \\ -p_z & 0 \\ 0 & -p_z \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix}] e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& [E_1 \partial_t - (\Sigma_{n=2,4,6} E_n \partial_{n/2})] \phi \\
& = -E_1 \partial_t \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{1}{E-m} \begin{pmatrix} \hat{p}_x & \hat{p}_y \\ -\hat{p}_y & \hat{p}_x \\ -\hat{p}_z & 0 \\ 0 & -\hat{p}_z \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& = -E_1 \partial_t \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})} \\
& - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}}{E-m} \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} e^{E_1(Et-\mathbf{p}\cdot\mathbf{r})}
\end{aligned}$$

$$\begin{aligned}
&= \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ E & 0 \\ 0 & E \end{pmatrix} e^{E_1(Et - \mathbf{p} \cdot \mathbf{r})} \\
&\quad - (\Sigma_{n=2,4,6} E_n \partial_{n/2}) \frac{\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}}{E-m} \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} e^{E_1(Et - \mathbf{p} \cdot \mathbf{r})} \\
&= E\psi_R - (\Sigma_{n=2,4,6} E_n \partial_{n/2})\psi_L.
\end{aligned}$$

Furthermore, $E\psi_R - (\Sigma_{n=2,4,6} E_n \partial_{n/2})\psi_L = -m\psi_R$

because $(\Sigma_{n=2,4,6} E_n \partial_{n/2})(\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2}) = (\Sigma_{n=3,5,7} E_n \hat{p}_{(n-1)/2})^2$

$$= \hat{p}_x^2 + \hat{p}_y^2 + \hat{p}_z^2$$

and $E - \frac{p_x^2 + p_y^2 + p_z^2}{E-m} = -m$ since $(E+m)(E-m) - (p_x^2 + p_y^2 + p_z^2) = 0$.**

Lorentz Invariance of Dirac equation:

$$\begin{aligned}
&\begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix} \begin{pmatrix} \partial_0 \psi_L \\ \partial_0 \psi_R \end{pmatrix} \\
&+ \Sigma_{n=2,4,6} \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix} \begin{pmatrix} \partial_{n/2} \psi_L \\ \partial_{n/2} \psi_R \end{pmatrix} = m \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}
\end{aligned}$$

Setting the Lorentz transform $\Lambda = \Lambda^T = \begin{pmatrix} \cosh(\alpha) & \sinh(\alpha) \\ \sinh(\alpha) & \cosh(\alpha) \end{pmatrix}$

we have by direct calculation

$$\Lambda \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix} \Lambda = \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix}$$

and

$$\Lambda \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix} \Lambda = \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix}$$

Then applying the Lorentz transform

$$\Lambda^T \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix} [\Lambda \begin{pmatrix} \partial'_0 \psi'_L \\ \partial'_0 \psi'_R \end{pmatrix}] \\ + \Sigma_{n=2,4,6} \Lambda^T \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix} [\Lambda \begin{pmatrix} \partial'_{n/2} \psi'_L \\ \partial'_{n/2} \psi'_R \end{pmatrix}] = m \begin{pmatrix} \psi'_L \\ \psi'_R \end{pmatrix}$$

which is equivalent to

$$[\Lambda^T \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix} \Lambda] \begin{pmatrix} \partial'_0 \psi'_L \\ \partial'_0 \psi'_R \end{pmatrix} \\ + \Sigma_{n=2,4,6} [\Lambda^T \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix} \Lambda] \begin{pmatrix} \partial'_{n/2} \psi'_L \\ \partial'_{n/2} \psi'_R \end{pmatrix} = m \begin{pmatrix} \psi'_L \\ \psi'_R \end{pmatrix}$$

and

$$\begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix} \begin{pmatrix} \partial'_0 \psi'_L \\ \partial'_0 \psi'_R \end{pmatrix} \\ + \Sigma_{n=2,4,6} \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix} \begin{pmatrix} \partial'_{n/2} \psi'_L \\ \partial'_{n/2} \psi'_R \end{pmatrix} = m \begin{pmatrix} \psi'_L \\ \psi'_R \end{pmatrix}$$

The Dirac Matrices in $M_{8 \times 8}\{0, \pm 1\}$:

The Pauli matrices are:

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

or, in terms of 4×4 matrices

$$\sigma_1 = E_3 = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \quad \sigma_2 = E_5 = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \\ \sigma_3 = E_7 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & -1 \end{pmatrix}$$

The Dirac matrices are:

$$\gamma^0 = \begin{pmatrix} I_2 & \mathbf{0} \\ \mathbf{0} & -I_2 \end{pmatrix} \quad \gamma^1 = \begin{pmatrix} \mathbf{0} & \sigma_1 \\ -\sigma_1 & \mathbf{0} \end{pmatrix}$$

$$\gamma^2 = \begin{pmatrix} \mathbf{0} & \sigma_2 \\ -\sigma_2 & \mathbf{0} \end{pmatrix} \quad \gamma^3 = \begin{pmatrix} \mathbf{0} & \sigma_3 \\ -\sigma_3 & \mathbf{0} \end{pmatrix}$$

or in terms of 8×8 matrices

$$\begin{aligned} \gamma^0 &= \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & -E_0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \end{pmatrix} \\ \gamma^1 &= \begin{pmatrix} \mathbf{0} & E_3 \\ -E_3 & \mathbf{0} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \\ \gamma^2 &= \begin{pmatrix} \mathbf{0} & E_5 \\ -E_5 & \mathbf{0} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix} \\ \gamma^3 &= \begin{pmatrix} \mathbf{0} & E_7 \\ -E_7 & \mathbf{0} \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \end{pmatrix} \end{aligned}$$

Their multiplication table is:

$\times$	γ^0	γ^1	γ^2	γ^3
γ^0	I	$\gamma^0\gamma^1$	$\gamma^0\gamma^2$	$\gamma^0\gamma^3$
γ^1	$-\gamma^0\gamma^1$	$-I$	$\gamma^1\gamma^2$	$\gamma^1\gamma^3$
γ^2	$-\gamma^0\gamma^2$	$-\gamma^1\gamma^2$	$-I$	$\gamma^2\gamma^3$
γ^3	$-\gamma^0\gamma^3$	$-\gamma^1\gamma^3$	$-\gamma^2\gamma^3$	$-I$

Referring back to the table:

$\times$	γ^0	γ^1	γ^2	γ^3
γ^0	I	$\gamma^0\gamma^1$	$\gamma^0\gamma^2$	$\gamma^0\gamma^3$
γ^1	$-\gamma^0\gamma^1$	$-I$	$\mathbf{k}I$	$-\mathbf{j}I$
γ^2	$-\gamma^0\gamma^2$	$-\mathbf{k}I$	$-I$	$\mathbf{i}I$
γ^3	$-\gamma^0\gamma^3$	$\mathbf{j}I$	$-\mathbf{i}I$	$-I$

We can use the current table to construct a representation of the quaternions in $M_{8 \times 8}\{0, \pm 1\}$:

$$(\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}) = (I, \gamma^2\gamma^3, \gamma^3\gamma^1, \gamma^1\gamma^2)$$

It is not difficult to check that this construction produces the required properties of quaternions.

Above we wrote the Dirac equation as::

$$\begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & -E_1 \end{pmatrix} \begin{pmatrix} \partial_0\psi_L \\ \partial_0\psi_R \end{pmatrix} + \sum_{n=2,4,6} \begin{pmatrix} \mathbf{0} & -E_n \\ E_n & \mathbf{0} \end{pmatrix} \begin{pmatrix} \partial_{n/2}\psi_L \\ \partial_{n/2}\psi_R \end{pmatrix} - m \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \mathbf{0}$$

Multiplying through by E_1 and changing sign throughout gives

$$\begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & -E_0 \end{pmatrix} \begin{pmatrix} \partial_0\psi_L \\ \partial_0\psi_R \end{pmatrix} + \sum_{n=3,5,7} \begin{pmatrix} \mathbf{0} & E_n \\ -E_n & \mathbf{0} \end{pmatrix} \begin{pmatrix} \partial_{(n-1)/2}\psi_L \\ \partial_{(n-1)/2}\psi_R \end{pmatrix} + m \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & E_1 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \mathbf{0}$$

which gives the more familiar form of the equation

$$\gamma^\mu \begin{pmatrix} \partial_\mu \psi_L \\ \partial_\mu \psi_R \end{pmatrix} + m \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & E_1 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \mathbf{0}$$

$$\text{Writing this as } (\gamma^0 \partial_t + \gamma^1 \partial_x + \gamma^2 \partial_y + \gamma^3 \partial_z) \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = -m \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & E_1 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$$

and applying the operator on both sides gives

$$\begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} (\partial_t^2 - \partial_x^2 - \partial_y^2 - \partial_z^2) \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = -m^2 \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$$

since the gammas anti-commute. A further discussion of the Klein-Gordon equation appears below.

The above gives two equations

$$E_0(\partial_t^2 - \partial_x^2 - \partial_y^2 - \partial_z^2)\psi_L = -m^2 E_0 \psi_L \text{ and}$$

$$E_0(\partial_t^2 - \partial_x^2 - \partial_y^2 - \partial_z^2)\psi_R = -m^2 E_0 \psi_R$$

The equation $(\partial_t^2 - \partial_x^2 - \partial_y^2 - \partial_z^2)\psi = -m^2 \psi$ applies to spin-less particles. However, Dirac particles satisfy the above two equations component-wise.

Proceeding in reverse, so to speak, we begin with

$$\begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} (\partial_t^2 - \partial_x^2 - \partial_y^2 - \partial_z^2) \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = -m^2 \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$$

and factor the operator

$$\begin{aligned} & (\gamma^0 \partial_t + \gamma^1 \partial_x + \gamma^2 \partial_y + \gamma^3 \partial_z)^2 \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} \\ &= -m \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & E_1 \end{pmatrix} (\gamma^0 \partial_t + \gamma^1 \partial_x + \gamma^2 \partial_y + \gamma^3 \partial_z) \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} \end{aligned}$$

Canceling the operator on each side restores the original Dirac equation

$$(\gamma^0 \partial_t + \gamma^1 \partial_x + \gamma^2 \partial_y + \gamma^3 \partial_z) \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = -m \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & E_1 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$$

restoring the spin characteristics of the solutions $\psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix}$.

Spinors:

Let ψ_i , $i = 1, 2, 3, 4$ be 2×2 matrix blocks.

For $\psi = \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix}$ an 8×2 spinor we can define its conjugate $\psi^* = \psi^T$ and $\bar{\psi} = \psi^* \gamma^0$.

Then for

$$\psi \in \left\{ \begin{pmatrix} E & 0 \\ 0 & E \\ 0 & 0 \\ 0 & 0 \\ p_z & 0 \\ 0 & p_z \\ p_x & -p_y \\ p_y & p_x \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ E & 0 \\ 0 & E \\ p_x & p_y \\ -p_y & p_x \\ -p_z & 0 \\ 0 & -p_z \end{pmatrix}, \begin{pmatrix} p_z & 0 \\ 0 & p_z \\ p_x & -p_y \\ p_y & p_x \\ E & 0 \\ 0 & E \\ 0 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} p_x & p_y \\ -p_y & p_x \\ -p_z & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ E & 0 \\ 0 & E \end{pmatrix} \right\},$$

$$\bar{\psi}\psi = \psi^* \gamma^0 \psi = \pm \begin{pmatrix} E^2 - p_x^2 - p_y^2 - p_z^2 & 0 \\ 0 & E^2 - p_x^2 - p_y^2 - p_z^2 \end{pmatrix} \text{ is Lorentz invariant where } \pm \text{ corresponds to particle/antiparticle.}$$

Rotation of Spinors:

$$\text{Let } \begin{pmatrix} a & -b \\ b & a \\ c & -d \\ d & c \end{pmatrix} \sim \begin{pmatrix} a + ib \\ c + id \end{pmatrix} \text{ be a } 4 \times 2 \text{ spinor.}$$

furthermore, let $\mathbf{n} = \frac{1}{\sqrt{n_x^2 + n_y^2 + n_z^2}}(n_x \mathbf{i} + n_y \mathbf{j} + n_z \mathbf{k})$ define the unit vector axis of the spinor.

Then $\mathbf{n} = \frac{1}{\sqrt{n_x^2 + n_y^2 + n_z^2}}(n_x E_2 + n_y E_4 + n_z E_6)$ and the rotation operator is

$$R(\theta) = \cos(\theta/2)E_0 + \sin(\theta/2)(n_x E_2 + n_y E_4 + n_z E_6).$$

Then written out explicitly,

$$\begin{aligned}
R(\theta) & \begin{pmatrix} a & -b \\ b & a \\ c & -d \\ d & c \end{pmatrix} \\
&= \begin{pmatrix} \cos(\theta/2) & n_z \sin(\theta/2) & -n_y \sin(\theta/2) & n_x \sin(\theta/2) \\ -n_z \sin(\theta/2) & \cos(\theta/2) & -n_x \sin(\theta/2) & -n_y \sin(\theta/2) \\ n_y \sin(\theta/2) & n_x \sin(\theta/2) & \cos(\theta/2) & -n_z \sin(\theta/2) \\ -n_x \sin(\theta/2) & n_y \sin(\theta/2) & n_z \sin(\theta/2) & \cos(\theta/2) \end{pmatrix} \begin{pmatrix} a & -b \\ b & a \\ c & -d \\ d & c \end{pmatrix}.
\end{aligned}$$

The Dirac Equation of a Charged Particle in an Electro-magnetic Field:

We can write the equation

$$\gamma^\mu \begin{pmatrix} \partial_\mu \psi_L \\ \partial_\mu \psi_R \end{pmatrix} + m \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & E_1 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \mathbf{0}$$

as

$$\gamma^\mu \begin{pmatrix} E_1 & \mathbf{0} \\ \mathbf{0} & E_1 \end{pmatrix} \begin{pmatrix} \partial_\mu \psi_L \\ \partial_\mu \psi_R \end{pmatrix} - m \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \mathbf{0}$$

We transform the momentum operator $\hat{p}_i \rightarrow \hat{p}_i + qE_0 A_i$ where $\mathbf{A}$ is an electromagnetic vector potential. That is, $E_1 \partial_i \rightarrow E_1 \partial_i - qE_0 A_i$.

Then we can write $\Sigma_{n=3,5,7} E_n (\hat{p}_{(n-1)/2} + qE_0 A_{(n-1)/2})$ as:

$$\Pi = \begin{pmatrix} \hat{p}_z + qE_0 A_z & 0 & \hat{p}_x + qE_0 A_x & \hat{p}_y + qE_0 A_y \\ 0 & \hat{p}_z + qE_0 A_z & -\hat{p}_y - qE_0 A_y & \hat{p}_x + qE_0 A_x \\ \hat{p}_x + qE_0 A_x & -\hat{p}_y - qE_0 A_y & -\hat{p}_z - qE_0 A_z & 0 \\ \hat{p}_y + qE_0 A_y & \hat{p}_x + qE_0 A_x & 0 & -\hat{p}_z - qE_0 A_z \end{pmatrix}$$

Then we have the following products:

$$\Pi \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} \hat{p}_z + qE_0 A_z & 0 \\ 0 & \hat{p}_z + qE_0 A_z \\ \hat{p}_x + qE_0 A_x & -\hat{p}_y - qE_0 A_y \\ \hat{p}_y - qE_0 A_y & \hat{p}_x + qE_0 A_x \end{pmatrix}$$

$$\text{and } \Pi \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} \hat{p}_x + qE_0A_x & \hat{p}_y + qE_0A_y \\ -\hat{p}_y - qE_0A_y & \hat{p}_x + qE_0A_x \\ -\hat{p}_z - qE_0A_z & 0 \\ 0 & -\hat{p}_z - qE_0A_z \end{pmatrix}$$

For $E \geq m$ two linearly independent solutions are

$$\phi = \left[\frac{1}{E+m} \begin{pmatrix} p_z + qA_z & 0 \\ 0 & p_z + qA_z \\ p_x + qA_x & -p_y - qA_y \\ p_y + qA_y & p_x + qA_x \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \right] e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

and

$$\phi = \left[\frac{1}{E+m} \begin{pmatrix} p_x + qA_x & p_y + qA_y \\ -p_y - qA_y & p_x + qA_x \\ -p_z - qA_z & 0 \\ 0 & -p_z - qA_z \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} \right] e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

For $E \leq -m$ two linearly independent solutions are

$$\phi = \left[\frac{1}{E-m} \begin{pmatrix} p_z + qA_z & 0 \\ 0 & p_z + qA_z \\ p_x + qA_x & -p_y - qA_y \\ p_y + qA_y & p_x + qA_x \end{pmatrix} - \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \right] e^{E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

and

$$\phi = \left[\frac{1}{E-m} \begin{pmatrix} p_x + qA_x & p_y + qA_y \\ -p_y - qA_y & p_x + qA_x \\ -p_z - qA_z & 0 \\ 0 & -p_z - qA_z \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix} \right] e^{E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

As in classic E-M theory, the gauge can be varied.

Let $A_i \rightarrow A'_i = A_i + \partial_i \chi(x)$. Then the solution $\psi' = e^{-E_1 q \chi} \psi$ since

$$\begin{aligned} (E_1 \partial_i - qE_0 A'_i) \psi' &= qE_0 \partial_i \chi \psi' + e^{-E_1 q \chi} E_1 \partial_i \psi - qE_0 A'_i \psi' \\ &= e^{-E_1 q \chi} qE_0 \partial_i \chi \psi + e^{-E_1 q \chi} E_1 \partial_i \psi - e^{-E_1 q \chi} qE_0 (A_i + \partial_i \chi) \psi \\ &= e^{-E_1 q \chi} [qE_0 \partial_i \chi + E_1 \partial_i - qE_0 A_i - qE_0 \partial_i \chi] \psi \\ &= e^{-E_1 q \chi} [E_1 \partial_i - qE_0 A_i] \psi \end{aligned}$$

So, the equation

$$\gamma^\mu \left[\begin{pmatrix} E_1 \partial_\mu & \mathbf{0} \\ \mathbf{0} & E_1 \partial_\mu \end{pmatrix} - q A'_\mu \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \right] \begin{pmatrix} \psi'_L \\ \psi'_R \end{pmatrix} - m \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \begin{pmatrix} \psi'_L \\ \psi'_R \end{pmatrix} = \mathbf{0}$$

is equivalent to

$$\gamma^\mu \left[\begin{pmatrix} E_1 \partial_\mu & \mathbf{0} \\ \mathbf{0} & E_1 \partial_\mu \end{pmatrix} - q A_\mu \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \right] \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} - m \begin{pmatrix} E_0 & \mathbf{0} \\ \mathbf{0} & E_0 \end{pmatrix} \begin{pmatrix} \psi_L \\ \psi_R \end{pmatrix} = \mathbf{0}$$

$e^{-E_1 q \chi}$ traces out a circular path around a torus and is isomorphic to S^1 . The group $\{e^{-E_1 \theta} : \theta \in \mathbf{R}(\text{mod } 2\pi)\} \sim U(1)$.

Isospin:

The theory of isospin uses the same mathematics as that developed for intrinsic spin.

Recall the Pauli matrices are:

$$\sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

and their multiplication table is:

$\times$	I	σ_1	σ_2	σ_3
I	I	σ_1	σ_2	σ_3
σ_1	σ_1	I	$i\sigma_3$	$-i\sigma_2$
σ_2	σ_2	$-i\sigma_3$	I	$i\sigma_1$
σ_3	σ_3	$i\sigma_2$	$-i\sigma_1$	I

Let $2\tau_1 = \sigma_1$, $2\tau_2 = \sigma_2$, and $2\tau_3 = \sigma_3$.

Then the τ multiplication table is

$\times$	I	$2\tau_1$	$2\tau_2$	$2\tau_3$
I	I	$2\tau_1$	$2\tau_2$	$2\tau_3$
$2\tau_1$	$2\tau_1$	I	$2i\tau_3$	$-2i\tau_2$
$2\tau_2$	$2\tau_2$	$-2i\tau_3$	I	$2i\tau_1$
$2\tau_3$	$2i\tau_3$	$2i\tau_2$	$-2i\tau_1$	I

Just as for intrinsic spin we have $S = \frac{1}{2}\sigma$ where $\sigma = \sigma_1 + \sigma_2 + \sigma_3$ and $S^2 = \frac{1}{4}(\sigma_1^2 + \sigma_2^2 + \sigma_3^2) = \frac{3}{4}I$ we also have $T = \tau$ where $\tau = \tau_1 + \tau_2 + \tau_3$ and $T^2 = \frac{1}{4}(\sigma_1^2 + \sigma_2^2 + \sigma_3^2) = \frac{3}{4}I$.

Let $p = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ represent a proton and $n = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ represent a neutron. They are to be regarded as the same particle in different isospin states.

The operator $2\tau_1$ transforms between the two isospin states

$$\text{that is, } 2\tau_1 p = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = n \text{ and } 2\tau_1 n = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = p$$

We can calculate the effects of τ_2 , and τ_3 on n and p .

$$\begin{aligned} 2\tau_2 n &= \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = -ip \text{ and } 2\tau_2 p = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = in \\ 2\tau_3 n &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = -n \text{ and } 2\tau_3 p = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = p \end{aligned}$$

We can form raising and lowering operators as

$$\tau_+ = \tau_1 + i\tau_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \text{ and } \tau_- = \tau_1 - i\tau_2 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$\text{Clearly, } \tau_+ n = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} = p$$

$$\text{and } \tau_- p = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} = n$$

The Klein-Gordon Equation:

The *Klein-Gordon* equation $(\partial_t^2 - \nabla^2)\psi = -m^2\psi$ has plane wave solutions of the form $\psi = e^{-i(Et - \mathbf{P} \cdot \mathbf{r})}$ since $\partial_t \psi = -iE\psi$, $\partial_x \psi = ip_x \psi$, $\partial_y \psi = ip_y \psi$, and $\partial_z \psi = ip_z \psi$. Then $(\partial_t^2 - \nabla^2)\psi = (-E^2 + p_x^2 + p_y^2 + p_z^2)\psi = -m^2\psi$ which is the 4-vector magnitude-squared $E^2 - p_x^2 - p_y^2 - p_z^2 = m^2$.

Expressed somewhat differently,

$$(\partial_t^2 - \nabla^2)\psi = \begin{pmatrix} \partial_t & \partial_x & \partial_y & \partial_z \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} \partial_t \\ \partial_x \\ \partial_y \\ \partial_z \end{pmatrix} \psi$$

$$\begin{aligned}
&= \begin{pmatrix} \partial_t & \partial_x & \partial_y & \partial_z \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} -iE\psi \\ ip_x\psi \\ ip_y\psi \\ ip_z\psi \end{pmatrix} \\
&= \begin{pmatrix} \partial_t & \partial_x & \partial_y & \partial_z \end{pmatrix} \begin{pmatrix} -iE\psi \\ -ip_x\psi \\ -ip_y\psi \\ -ip_z\psi \end{pmatrix} \\
&= ((-iE)^2 + (-ip_x)(ip_x) + (-ip_y)(ip_y) + (-ip_z)(ip_z))\psi
\end{aligned}$$

$= (-E^2 + p_x^2 + p_y^2 + p_z^2)\psi = -m^2\psi$. which is consistent with the 4-vector magnitude-squared $E^2 - p_x^2 - p_y^2 - p_z^2 = m^2$. This describes an unbound spinless particle with mass m .

The Klein-Gordon equation is invariant under a Lorentz transformation Λ since it preserves the Minkowski metric. That is,

$$\begin{aligned}
&\begin{pmatrix} \partial_{t'} & \partial_{x'} & \partial_{y'} & \partial_{z'} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} \partial_{t'} \\ \partial_{x'} \\ \partial_{y'} \\ \partial_{z'} \end{pmatrix} \psi \\
&= \left[\Lambda \begin{pmatrix} \partial_t \\ \partial_x \\ \partial_y \\ \partial_z \end{pmatrix} \right]^T \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \Lambda \begin{pmatrix} \partial_t \\ \partial_x \\ \partial_y \\ \partial_z \end{pmatrix} \psi \\
&= \begin{pmatrix} \partial_t & \partial_x & \partial_y & \partial_z \end{pmatrix} \Lambda^T \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \Lambda \begin{pmatrix} \partial_t \\ \partial_x \\ \partial_y \\ \partial_z \end{pmatrix} \psi \\
&= \begin{pmatrix} \partial_t & \partial_x & \partial_y & \partial_z \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} \partial_t \\ \partial_x \\ \partial_y \\ \partial_z \end{pmatrix} \psi
\end{aligned}$$

The D'Alembert operator $\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2$ in the relativistic wave equation

$$\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) \psi = 0$$

can be expressed as $\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 = \left(\frac{1}{c} \gamma^0 \frac{\partial}{\partial t} + \gamma^1 \frac{\partial}{\partial x} + \gamma^2 \frac{\partial}{\partial y} + \gamma^3 \frac{\partial}{\partial z} \right)^2$.

Suppose $(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2)\psi = k^2\psi = -\frac{m^2 c^2}{\hbar^2}\psi$

Then the solution must satisfy

$$(\frac{1}{c} \gamma^0 \frac{\partial}{\partial t} + \gamma^1 \frac{\partial}{\partial x} + \gamma^2 \frac{\partial}{\partial y} + \gamma^3 \frac{\partial}{\partial z})\psi = \pm k\psi \text{ since}$$

$$(\frac{1}{c} \gamma^0 \frac{\partial}{\partial t} + \gamma^1 \frac{\partial}{\partial x} + \gamma^2 \frac{\partial}{\partial y} + \gamma^3 \frac{\partial}{\partial z})^2 \psi$$

$$= (\frac{1}{c} \gamma^0 \frac{\partial}{\partial t} + \gamma^1 \frac{\partial}{\partial x} + \gamma^2 \frac{\partial}{\partial y} + \gamma^3 \frac{\partial}{\partial z})(\pm k\psi) = k^2\psi.$$

$$\text{Then } (\gamma^0 \frac{\partial}{\partial t} + c\gamma^1 \frac{\partial}{\partial x} + c\gamma^2 \frac{\partial}{\partial y} + c\gamma^3 \frac{\partial}{\partial z})\psi = \pm i \frac{mc}{\hbar} \psi.$$

Setting $c = 1$, we get the Dirac equation(s) $(i\hbar\gamma^\mu\partial_\mu \mp m)\psi = 0$ discussed previously.

The D'Alembert operator can also be expressed as

$$\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \simeq (\mathbf{1} \frac{\partial}{c\partial t})^2 + (\mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z})^2 \text{ or with } c = 1$$

$$\frac{\partial^2}{\partial t^2} - \nabla^2 \simeq (\mathbf{1} \frac{\partial}{\partial t})^2 + (\mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y} + \mathbf{k} \frac{\partial}{\partial z})^2$$

$$= \begin{pmatrix} \partial/\partial t & \partial/\partial x & \partial/\partial y & \partial/\partial z \end{pmatrix} \begin{pmatrix} \mathbf{11} & 0 & 0 & 0 \\ 0 & \mathbf{ii} & 0 & 0 \\ 0 & 0 & \mathbf{jj} & 0 \\ 0 & 0 & 0 & \mathbf{kk} \end{pmatrix} \begin{pmatrix} \partial/\partial t \\ \partial/\partial x \\ \partial/\partial y \\ \partial/\partial z \end{pmatrix}$$

We use the covariant derivative to get the general wave equation operator:

$$\begin{pmatrix} \nabla_t & \nabla_u & \nabla_v & \nabla_w \end{pmatrix} \mathbf{G}^{-1} \begin{pmatrix} \nabla_t \\ \nabla_u \\ \nabla_v \\ \nabla_w \end{pmatrix}$$

$$\text{where } \mathbf{G}^{-1} = \begin{pmatrix} \langle \frac{\partial}{\partial t}, \frac{\partial}{\partial t} \rangle^{-1} \mathbf{11} & 0 & 0 & 0 \\ 0 & \langle \frac{\partial}{\partial u}, \frac{\partial}{\partial u} \rangle^{-1} \mathbf{e}_u \mathbf{e}_u & 0 & 0 \\ 0 & 0 & \langle \frac{\partial}{\partial v}, \frac{\partial}{\partial v} \rangle^{-1} \mathbf{e}_v \mathbf{e}_v & 0 \\ 0 & 0 & 0 & \langle \frac{\partial}{\partial w}, \frac{\partial}{\partial w} \rangle^{-1} \mathbf{e}_w \mathbf{e}_w \end{pmatrix}$$

$$\text{and } \mathbf{G} = \begin{pmatrix} \langle \frac{\partial}{\partial t}, \frac{\partial}{\partial t} \rangle \mathbf{1}\mathbf{1} & 0 & 0 & 0 \\ 0 & \langle \frac{\partial}{\partial u}, \frac{\partial}{\partial u} \rangle \mathbf{e}_u \mathbf{e}_u & 0 & 0 \\ 0 & 0 & \langle \frac{\partial}{\partial v}, \frac{\partial}{\partial v} \rangle \mathbf{e}_v \mathbf{e}_v & 0 \\ 0 & 0 & 0 & \langle \frac{\partial}{\partial w}, \frac{\partial}{\partial w} \rangle \mathbf{e}_w \mathbf{e}_w \end{pmatrix}$$

and where the coordinates t, u, v, w are associated with the quaternion basis $\mathbf{1}, \mathbf{e}_u, \mathbf{e}_v, \mathbf{e}_w$.

Recall from *Quaternion Space-Time* that for a 4-vector $\mathbf{V}$,

$$\|\mathbf{V}\|^2 = \mathbf{V}^T \mathbf{G} \mathbf{V}.$$

The wave equation operator is most easily calculated using the 4D form of the Laplacian:

$$\nabla^2 = \frac{1}{\sqrt{-g}} \partial_\mu (\sqrt{-g} g^{\mu\nu} \partial_\nu).$$

For R-W spherical coordinates,

$$\text{where } \mathbf{G} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -R^2 & 0 & 0 \\ 0 & 0 & -R^2 \sin^2 \chi & 0 \\ 0 & 0 & 0 & -R^2 \sin^2 \chi \sin^2 \theta \end{pmatrix} \mathbf{1}$$

$$\text{Then } \frac{1}{\sqrt{-g}} \partial_t (\sqrt{-g} g^{tt} \partial_t) = \partial_t^2 + \frac{1}{\sqrt{-g}} \partial_t (\sqrt{-g}) \partial_t = 6R^{-1} \dot{R} \partial_t + \partial_t^2$$

$$\text{and for } S^3, \nabla_{S^3}^2 = \frac{1}{\sqrt{\eta}} \partial_i (\sqrt{\eta} \eta^{ij} \partial_j) = \frac{1}{\sqrt{\eta}} [\partial_\chi (\sqrt{\eta} \eta^{\chi\chi} \partial_\chi) + \partial_\theta (\sqrt{\eta} \eta^{\theta\theta} \partial_\theta) + \partial_\phi (\sqrt{\eta} g^{\phi\phi} \partial_\phi)]$$

$$\text{where } \eta_{ij} = \begin{pmatrix} R^2 & 0 & 0 \\ 0 & R^2 \sin^2 \chi & 0 \\ 0 & 0 & R^2 \sin^2 \chi \sin^2 \theta \end{pmatrix}$$

$$\text{and } \eta = \text{Det}(\eta_{ij}) = R^6 \sin^4 \chi \sin^2 \theta$$

$$\text{and } \sqrt{\eta} = \sqrt{\text{Det}(\eta_{ij})} = R^3 \sin^2 \chi \sin \theta$$

Then

$$\nabla_{S^3}^2 = \frac{1}{\sqrt{g}} [2R^3 \sin \chi \cos \chi \sin \theta R^{-2} \partial_\chi + R^3 \sin^2 \chi \sin \theta R^{-2} \partial_\chi^2$$

$$\begin{aligned}
& +R^3 \sin^2 \chi \cos \theta (R^2 \sin^2 \chi)^{-1} \partial_\theta + R^3 \sin^2 \chi \sin \theta (R^2 \sin^2 \chi)^{-1} \partial_\theta^2 \\
& +R^3 \sin^2 \chi \sin \theta (R^2 \sin^2 \chi \sin^2 \theta)^{-1} \partial_\phi^2] \\
\nabla_{S^3}^2 &= \frac{1}{\sqrt{g}} [2R \sin \chi \cos \chi \sin \theta \partial_\chi + R \sin^2 \chi \sin \theta \partial_\chi^2 \\
& +R \cos \theta \partial_\theta + R \sin \theta \partial_\theta^2 + R \csc \theta \partial_\phi^2] \\
\nabla_{S^3}^2 &= \frac{1}{R^2 \sin^2 \chi \sin \theta} [2 \sin \chi \cos \chi \sin \theta \partial_\chi + \sin^2 \chi \sin \theta \partial_\chi^2 + \sin \chi \cos \theta \partial_\theta + \sin \theta \partial_\theta^2 \\
& + \csc \theta \partial_\phi^2] \\
&= \frac{1}{R^2} [2 \cot \chi \partial_\chi + \partial_\chi^2 + \csc \chi \cot \theta \partial_\theta + \csc^2 \chi \partial_\theta^2 + \csc^2 \chi \csc^2 \theta \partial_\phi^2]
\end{aligned}$$

So, in Robertson-Walker coordinates on $\mathbf{R}^+ \times S^3$, the wave equation operator is,

$$\begin{aligned}
& \frac{\partial^2}{\partial t^2} + 6R^{-1} \dot{R} \partial_t - \nabla_{S^3}^2 \\
&= \frac{\partial^2}{\partial t^2} + 6R^{-1} \dot{R} \partial_t - \frac{1}{R^2} [2 \cot \chi \partial_\chi + \partial_\chi^2 + \csc \chi \cot \theta \partial_\theta + \csc^2 \chi \partial_\theta^2 + \csc^2 \chi \csc^2 \theta \partial_\phi^2]
\end{aligned}$$

The above equation is satisfied if both of the following equations are solved simultaneously:

$$\frac{\partial^2}{\partial t^2} \psi = \frac{1}{R^2} [\partial_\chi^2 + \csc^2 \chi \partial_\theta^2 + \csc^2 \chi \csc^2 \theta \partial_\phi^2] \psi \quad (9)$$

$$6R^{-1} \dot{R} \partial_t \psi = \frac{1}{R^2} [2 \cot \chi \partial_\chi + \csc \chi \cot \theta \partial_\theta] \psi \quad (10)$$

To solve (9) set $\psi = e^{Et + \Xi(\chi) + \Theta(\theta) + \Phi(\phi)}$

Then $E^2 \psi = \frac{1}{R^2} [(\Xi'' + \Xi'^2) + \csc^2 \chi (\Theta'' + \Theta'^2) + \csc^2 \chi \csc^2 \theta (\Phi'' + \Phi'^2)] \psi$

and $E^2 \psi - \frac{1}{R^2} [(\Xi'' + \Xi'^2) + \csc^2 \chi (\Theta'' + \Theta'^2) + \csc^2 \chi \csc^2 \theta (\Phi'' + \Phi'^2)] \psi = 0$

So, $[E^2 + g^{\chi\chi}(\Xi'' + \Xi'^2) + g^{\theta\theta}(\Theta'' + \Theta'^2) + g^{\phi\phi}(\Phi'' + \Phi'^2)] \psi = 0$

while at the same time $(E^2 + g_{\chi\chi} P_\chi^2 + g_{\theta\theta} P_\theta^2 + g_{\phi\phi} P_\phi^2) \psi = 0$

$$\text{Setting } \Xi'' + \Xi'^2 = g_{\chi\chi}^2 P_\chi^2, \Theta'' + \Theta'^2 = g_{\theta\theta}^2 P_\theta^2, \Phi'' + \Phi'^2 = g_{\phi\phi}^2 P_\phi^2$$

We have Ξ , Θ , and Φ as the solutions to the following differential equations:

$$\Xi'' + \Xi'^2 - g_{\chi\chi}^2 P_\chi^2 = 0; \Theta'' + \Theta'^2 - g_{\theta\theta}^2 P_\theta^2 = 0; \Phi'' + \Phi'^2 - g_{\phi\phi}^2 P_\phi^2 = 0$$

In the special case where energy and momentum are constant the second derivatives are zero so we have the solutions for (9):

$$\psi = e^{\pm i(Et - R^2 P_\chi \chi - R^2 \sin^2 \chi P_\theta \theta - R^2 \sin^2 \chi \sin^2 \theta P_\phi \phi)}$$

From (10) we get:

$$HE = \frac{1}{6R^2} [2\cot\chi\Xi' + \csc\chi\cot\theta\Theta'] \text{ where } H \text{ is the Hubble parameter.}$$

If both (9) and (10) are satisfied then the mixed equation will be satisfied but it is possible for a solution to satisfy the mixed equation without satisfying either (9) or (10). Such a situation could indicate the presence of 'exotic' matter.

To determine the wave equation in Schwarzschild coordinates we again use the 4D Laplacian.

$$\nabla^2 = \frac{1}{\sqrt{-g}} \partial_\mu (\sqrt{-g} g^{\mu\nu} \partial_\nu).$$

For $\mathbf{R}^+ \times \mathbf{R}^+ \times S^2$,

$$\nabla^2 = \frac{1}{\sqrt{-g}} \partial_\alpha (\sqrt{-g} g^{\alpha\beta} \partial_\beta) = \frac{1}{\sqrt{-g}} [\partial_t (\sqrt{-g} g^{tt} \partial_t) + \partial_R (\sqrt{-g} g^{RR} \partial_R) + \partial_\theta (\sqrt{-g} g^{\theta\theta} \partial_\theta) + \partial_\phi (\sqrt{-g} g^{\phi\phi} \partial_\phi)]$$

$$\text{where } g_{\alpha\beta} = \begin{pmatrix} \kappa_R & 0 & 0 & 0 \\ 0 & -\kappa_R^{-1} & 0 & 0 \\ 0 & 0 & -R^2 & 0 \\ 0 & 0 & 0 & -R^2 \sin^2 \theta \end{pmatrix}$$

$$\text{and } g = \text{Det}(g_{\alpha\beta}) = -R^4 \sin^2 \theta$$

$$\text{and } \sqrt{-g} = R^2 \sin \theta$$

Then

$$\begin{aligned}
\nabla^2 = & \frac{1}{\sqrt{-g}} [\partial_t(\sqrt{-g})g^{tt}\partial_t + \partial_t(g^{tt})\sqrt{-g}\partial_t + \sqrt{-g}g^{tt}\partial_t^2 \\
& + \partial_R(\sqrt{-g})g^{RR}\partial_R + \partial_R(g^{RR})\sqrt{-g}\partial_R + \sqrt{-g}g^{RR}\partial_R^2 \\
& + \partial_\theta(\sqrt{-g})g^{\theta\theta}\partial_\theta + \partial_\theta(g^{\theta\theta})\sqrt{-g}\partial_\theta + \sqrt{-g}g^{\theta\theta}\partial_\theta^2 \\
& + \partial_\phi(\sqrt{-g})g^{\phi\phi}\partial_\phi + \partial_\phi(g^{\phi\phi})\sqrt{-g}\partial_\phi + \sqrt{-g}g^{\phi\phi}\partial_\phi^2]
\end{aligned}$$

Then

$$\begin{aligned}
\nabla^2 = & \frac{1}{\sqrt{-g}} \left[\frac{R^2 \sin \theta}{\kappa_R} \partial_t^2 + \partial_R(\sqrt{-g})g^{RR}\partial_R + \partial_R(g^{RR})\sqrt{-g}\partial_R + \sqrt{-g}g^{RR}\partial_R^2 \right. \\
& + \partial_\theta(\sqrt{-g})g^{\theta\theta}\partial_\theta + \partial_\theta(g^{\theta\theta})\sqrt{-g}\partial_\theta + \sqrt{-g}g^{\theta\theta}\partial_\theta^2 \\
& \left. + \partial_\phi(\sqrt{-g})g^{\phi\phi}\partial_\phi + \partial_\phi(g^{\phi\phi})\sqrt{-g}\partial_\phi + \sqrt{-g}g^{\phi\phi}\partial_\phi^2 \right]
\end{aligned}$$

Then

$$\begin{aligned}
\nabla^2 = & \kappa_R^{-1} \partial_t^2 + \frac{1}{\sqrt{-g}} [\partial_R(\sqrt{-g})g^{RR}\partial_R + \partial_R(g^{RR})\sqrt{-g}\partial_R + \sqrt{-g}g^{RR}\partial_R^2 \\
& + \partial_\theta(\sqrt{-g})g^{\theta\theta}\partial_\theta + \partial_\theta(g^{\theta\theta})\sqrt{-g}\partial_\theta + \sqrt{-g}g^{\theta\theta}\partial_\theta^2 \\
& + \partial_\phi(\sqrt{-g})g^{\phi\phi}\partial_\phi + \partial_\phi(g^{\phi\phi})\sqrt{-g}\partial_\phi + \sqrt{-g}g^{\phi\phi}\partial_\phi^2] \\
= & \kappa_R^{-1} \partial_t^2 - \frac{1}{\sqrt{\eta}} [\partial_R(\sqrt{\eta})\eta^{RR}\partial_R + \partial_R(\eta^{RR})\sqrt{\eta}\partial_R + \sqrt{\eta}\eta^{RR}\partial_R^2 \\
& + \partial_\theta(\sqrt{\eta})\eta^{\theta\theta}\partial_\theta + \partial_\theta(\eta^{\theta\theta})\sqrt{\eta}\partial_\theta + \sqrt{\eta}\eta^{\theta\theta}\partial_\theta^2 \\
& + \partial_\phi(\sqrt{\eta})\eta^{\phi\phi}\partial_\phi + \partial_\phi(\eta^{\phi\phi})\sqrt{\eta}\partial_\phi + \sqrt{\eta}\eta^{\phi\phi}\partial_\phi^2]
\end{aligned}$$

$$\text{where } \eta_{ij} = \begin{pmatrix} \kappa_R^{-1} & 0 & 0 \\ 0 & R^2 & 0 \\ 0 & 0 & R^2 \sin^2 \theta \end{pmatrix}$$

$$\text{and } \eta = \text{Det}(\eta_{ij}) = \kappa_R^{-1} R^4 \sin^2 \theta$$

$$\text{and } \sqrt{\eta} = \kappa_R^{-1/2} R^2 \sin \theta$$

$$\text{We set } \nabla_{\mathbf{R}^+ \times S^2}^2 = \frac{1}{\sqrt{\eta}} [\partial_R(\sqrt{\eta})\eta^{RR}\partial_R + \partial_R(\eta^{RR})\sqrt{\eta}\partial_R + \sqrt{\eta}\eta^{RR}\partial_R^2$$

$$\begin{aligned}
& +\partial_\theta(\sqrt{\eta})\eta^{\theta\theta}\partial_\theta + \partial_\theta(\eta^{\theta\theta})\sqrt{\eta}\partial_\theta + \sqrt{\eta}\eta^{\theta\theta}\partial_\theta^2 \\
& +\partial_\phi(\sqrt{\eta})\eta^{\phi\phi}\partial_\phi + \partial_\phi(\eta^{\phi\phi})\sqrt{\eta}\partial_\phi + \sqrt{\eta}\eta^{\phi\phi}\partial_\phi^2] \\
& = \frac{1}{\sqrt{\eta}}[\partial_R(\sqrt{\eta}\eta^{RR})\partial_R + \sqrt{\eta}\eta^{RR}\partial_R^2 \\
& +\partial_\theta(\sqrt{\eta}\eta^{\theta\theta})\partial_\theta + \sqrt{\eta}\eta^{\theta\theta}\partial_\theta^2 \\
& +\partial_\phi(\sqrt{\eta}\eta^{\phi\phi})\partial_\phi + \sqrt{\eta}\eta^{\phi\phi}\partial_\phi^2] \\
& = \frac{1}{\sqrt{\eta}}[\partial_R(R^2\sin\theta)\partial_R + R^2\sin\theta\partial_R^2 \\
& +\partial_\theta(\kappa_R^{-1/2}\sin\theta)\partial_\theta + \kappa_R^{-1/2}\sin\theta\partial_\theta^2 \\
& +\partial_\phi(\kappa_R^{-1/2})\partial_\phi + \kappa_R^{-1/2}\partial_\phi^2] \\
& = \frac{1}{\sqrt{\eta}}[2R\sin\theta\partial_R + R^2\sin\theta\partial_R^2 + \kappa_R^{-1/2}\cos\theta\partial_\theta + \kappa_R^{-1/2}\sin\theta\partial_\theta^2 + \kappa_R^{-1/2}\partial_\phi^2] \\
& = \frac{1}{R^2}[2R\kappa_R^{1/2}\partial_R + R^2\kappa_R^{1/2}\partial_R^2 + \cot\theta\partial_\theta + \partial_\theta^2 + \csc\theta\partial_\phi^2]
\end{aligned}$$

Then the wave equation operator in Schwarzschild coordinates is

$$\begin{aligned}
& \kappa_R^{-1}\partial_t^2 - \nabla_{\mathbf{R}^+ \times S^2}^2 \\
& = \kappa_R^{-1}\partial_t^2 - \frac{1}{R^2}[2R\kappa_R^{1/2}\partial_R + R^2\kappa_R^{1/2}\partial_R^2 + \cot\theta\partial_\theta + \partial_\theta^2 + \csc\theta\partial_\phi^2]
\end{aligned}$$

In the weak field limit where $\kappa_R \approx 1$, $\nabla_{\mathbf{R}^+ \times S^2}^2$ reduces to the Laplacian in ordinary polar coordinates. So, in the weak field limit the operator is as mentioned above, $\frac{\partial^2}{\partial t^2} - \nabla^2$.

Referring back to the article *The Z-field (Energy-Momentum)* we can now summarize. We will call Type 1 equations the set $\{(9), (10), (12), (14)\}$ in that article and Type 2 the set $\{(9), (11), (13), (15)\}$.

Bosons:–Satisfy Type 1 with wavelength λ – Satisfy Klein-Gordon Eqn with $p = \frac{hc}{\lambda}$

Fermions:–Satisfy Type 2 with wavelength λ – Satisfy Dirac eqn with $p = \frac{hc}{\lambda}$

Footnote*: These matrices are constructed as follows:

Start with the quaternions in $M_{4 \times 4}\{0, \pm 1\}$

$$\mathbf{1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \mathbf{i} = \begin{pmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

$$\mathbf{j} = \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \end{pmatrix} \quad \mathbf{k} = \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}.$$

Then form the matrices $\mathbf{ii}, \mathbf{ij}, \mathbf{ik}$

$$\text{where } \mathbf{i} = \begin{pmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

Then

$$(E_0, E_1, E_2, E_3, E_4, E_5, E_6, E_7) = (\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{ii}, \mathbf{j}, \mathbf{ij}, \mathbf{k}, \mathbf{ik})$$

As stated previously, their multiplication table is

$\times$	E_0	E_1	E_2	E_3	E_4	E_5	E_6	E_7
E_0	E_0	E_1	E_2	E_3	E_4	E_5	E_6	E_7
E_1	E_1	$-E_0$	E_3	$-E_2$	E_5	$-E_4$	E_7	$-E_6$
E_2	E_2	E_3	$-E_0$	$-E_1$	E_6	E_7	$-E_4$	$-E_5$
E_3	E_3	$-E_2$	$-E_1$	E_0	E_7	$-E_6$	$-E_5$	E_4
E_4	E_4	E_5	$-E_6$	$-E_7$	$-E_0$	$-E_1$	E_2	E_3
E_5	E_5	$-E_4$	$-E_7$	E_6	$-E_1$	E_0	E_3	$-E_2$
E_6	E_6	E_7	E_4	E_5	$-E_2$	$-E_3$	$-E_0$	$-E_1$
E_7	E_7	$-E_6$	E_5	$-E_4$	$-E_3$	E_2	$-E_1$	E_0

Octonians:

The following is the Cayley-Graves multiplication table for the octonians. (<http://en.wikipedia.org/wiki/Octonion>)

$\times$	e_0	e_1	e_2	e_3	e_4	e_5	e_6	e_7
e_0	e_0	e_1	e_2	e_3	e_4	e_5	e_6	e_7
e_1	e_1	$-e_0$	e_3	$-e_2$	e_5	$-e_4$	$(-e_7)$	(e_6)
e_2	e_2	$(-e_3)$	$-e_0$	(e_1)	e_6	e_7	$-e_4$	$-e_5$
e_3	e_3	(e_2)	$-e_1$	$(-e_0)$	e_7	$-e_6$	(e_5)	$(-e_4)$
e_4	e_4	$(-e_5)$	$-e_6$	$-e_7$	$-e_0$	(e_1)	e_2	e_3
e_5	e_5	(e_4)	$-e_7$	e_6	$-e_1$	$(-e_0)$	$(-e_3)$	(e_2)
e_6	e_6	e_7	e_4	$(-e_5)$	$-e_2$	(e_3)	$-e_0$	$-e_1$
e_7	e_7	$-e_6$	e_5	(e_4)	$-e_3$	$(-e_2)$	(e_1)	$(-e_0)$

Comparing this table to that for the E s derived above we can make the association $e_i \leftrightarrow E_i$. Then $e_i e_j \leftrightarrow E_i E_j$ except for the entries in parentheses in which case $e_i e_j \leftrightarrow -E_i E_j$.

We observe a similar structure for the odd octonians

$\times$	e_0	e_3	e_5	e_7
e_0	e_0	e_3	e_5	e_7
e_3	e_3	$(-e_0)$	$-e_1 e_7$	$e_1 e_5$
e_5	e_5	$e_1 e_7$	$(-e_0)$	$-e_1 e_3$
e_7	e_7	$-e_1 e_5$	$e_1 e_3$	$(-e_0)$

as for the Pauli matrices

$\times$	I	σ_1	σ_2	σ_3
I	I	σ_1	σ_2	σ_3
σ_1	σ_1	I	$i\sigma_3$	$-i\sigma_2$
σ_2	σ_2	$-i\sigma_3$	I	$i\sigma_1$
σ_3	σ_3	$i\sigma_2$	$-i\sigma_1$	I

Let $\phi(\pm\sigma_1, \pm\sigma_2, \pm\sigma_3) = (\pm e_3, \pm e_5, \pm e_7)$. Then $e_1 \phi(xy/i) = -\phi(x)\phi(y)$.

Footnote**:

The solution

$$\phi = \left[\frac{1}{E+m} \begin{pmatrix} \hat{p}_z & 0 \\ 0 & \hat{p}_z \\ \hat{p}_x & -\hat{p}_y \\ \hat{p}_y & \hat{p}_x \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \right] e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})}$$

to the Dirac equation involves a slight abuse of notation.

Let $\theta = Et - \mathbf{p} \cdot \mathbf{r}$

$e^{-E_1\theta}$ is the 4×4 matrix

$$e^{-E_1\theta} = \begin{pmatrix} \cos\theta & \sin\theta & 0 & 0 \\ -\sin\theta & \cos\theta & 0 & 0 \\ 0 & 0 & \cos\theta & \sin\theta \\ 0 & 0 & -\sin\theta & \cos\theta \end{pmatrix} = \cos\theta E_0 - \sin\theta E_1.$$

$$\begin{pmatrix} \hat{p}_z & 0 \\ 0 & \hat{p}_z \\ \hat{p}_x & -\hat{p}_y \\ \hat{p}_y & \hat{p}_x \end{pmatrix} e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})} \text{ is to be understood to mean}$$

$$\begin{aligned} & \begin{pmatrix} \hat{p}_z(\cos\theta E_0 - \sin\theta E_1) & 0 \\ 0 & \hat{p}_z(\cos\theta E_0 - \sin\theta E_1) \\ \hat{p}_x(\cos\theta E_0 - \sin\theta E_1) & -\hat{p}_y(\cos\theta E_0 - \sin\theta E_1) \\ \hat{p}_y(\cos\theta E_0 - \sin\theta E_1) & \hat{p}_x(\cos\theta E_0 - \sin\theta E_1) \end{pmatrix} \\ &= -E_1 \begin{pmatrix} \partial_z(\cos\theta E_0 - \sin\theta E_1) & 0 \\ 0 & \partial_z(\cos\theta E_0 - \sin\theta E_1) \\ \partial_x(\cos\theta E_0 - \sin\theta E_1) & -\partial_y(\cos\theta E_0 - \sin\theta E_1) \\ \partial_y(\cos\theta E_0 - \sin\theta E_1) & \partial_x(\cos\theta E_0 - \sin\theta E_1) \end{pmatrix} \\ &= -E_1 \begin{pmatrix} -p_z(-\sin\theta E_0 - \cos\theta E_1) & 0 \\ 0 & -p_z(-\sin\theta E_0 - \cos\theta E_1) \\ -p_x(-\sin\theta E_0 - \cos\theta E_1) & p_y(-\sin\theta E_0 - \cos\theta E_1) \\ -p_y(-\sin\theta E_0 - \cos\theta E_1) & -p_x(-\sin\theta E_0 - \cos\theta E_1) \end{pmatrix} \\ &= -E_1 \begin{pmatrix} p_z(\sin\theta E_0 + \cos\theta E_1) & 0 \\ 0 & p_z(\sin\theta E_0 + \cos\theta E_1) \\ p_x(\sin\theta E_0 + \cos\theta E_1) & -p_y(\sin\theta E_0 + \cos\theta E_1) \\ p_y(\sin\theta E_0 + \cos\theta E_1) & p_x(\sin\theta E_0 + \cos\theta E_1) \end{pmatrix} \\ &= \begin{pmatrix} p_z(\cos\theta E_0 - \sin\theta E_1) & 0 \\ 0 & p_z(\cos\theta E_0 - \sin\theta E_1) \\ p_x(\cos\theta E_0 - \sin\theta E_1) & -p_y(\cos\theta E_0 - \sin\theta E_1) \\ p_y(\cos\theta E_0 - \sin\theta E_1) & p_x(\cos\theta E_0 - \sin\theta E_1) \end{pmatrix} \\ &= \begin{pmatrix} p_z & 0 \\ 0 & p_z \\ p_x & -p_y \\ p_y & p_x \end{pmatrix} e^{-E_1(Et - \mathbf{p} \cdot \mathbf{r})}. \end{aligned}$$

It should also be noted that there is a diffeomorphism

$$\begin{pmatrix} \cos\theta & \sin\theta & 0 & 0 \\ -\sin\theta & \cos\theta & 0 & 0 \\ 0 & 0 & \cos\theta & \sin\theta \\ 0 & 0 & -\sin\theta & \cos\theta \end{pmatrix} \leftrightarrow \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix}$$

indicating that θ traces out the equivalent of a circular path around the torus

$$\begin{pmatrix} \cos\theta & \sin\theta & 0 & 0 \\ -\sin\theta & \cos\theta & 0 & 0 \\ 0 & 0 & \cos\phi & \sin\phi \\ 0 & 0 & -\sin\phi & \cos\phi \end{pmatrix}$$

So, in fact $e^{-E_1(Et-\mathbf{P}\cdot\mathbf{r})} \simeq e^{-i(Et-\mathbf{P}\cdot\mathbf{r})}$

and our solution can be written as

$$\phi = [\frac{1}{E+m} \begin{pmatrix} \hat{p}_z & 0 \\ 0 & \hat{p}_z \\ \hat{p}_x & -\hat{p}_y \\ \hat{p}_y & \hat{p}_x \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}] e^{-i(Et-\mathbf{P}\cdot\mathbf{r})}$$

or as

$$\phi = [\frac{1}{E+m} \begin{pmatrix} \hat{p}_z \\ \hat{p}_x + i\hat{p}_y \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \end{pmatrix}] e^{-i(Et-\mathbf{P}\cdot\mathbf{r})}$$

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